

We are pleased to offer a 2-day course which will qualify certified and/or licensed practitioners to fit the Dynamic Arm. Practitioners who successfully complete this training course will receive a *Certificate of Completion* and will be placed on our list of "Otto Bock DynamicArm Qualified Practitioners" making them eligible to purchase additional Dynamic Arms for other qualified patients.

Course Prerequisites:

- Practitioner must be certified and/or licensed in order to attend the Dynamic Arm course
- Practitioner must have attended a MyoBock certification course within the past 3 years
- Attend with a patient and bring a well fitted socket with appropriate suspension. (See socket requirements below.) Patient can be a Transhumeral Level or higher.
- Purchase of a Dynamic Arm for the patient and ElbowSoft programming software is required
- Bring a laptop computer that meets the following system requirements:
 - PC with Windows XP SP2 or Windows Vista (32-bit). Otto Bock software is **NOT** compatible with 64-bit operating systems.
 - Screen resolution of 1024 x 768 or higher
 - CD-ROM Drive and available USB port
- Install ElbowSoft prior to the course. The installation disk will be sent out upon receipt of the registration form. A license number is required to complete installation. Follow the prompts in the software.

To successfully complete the 2-day course, the practitioner must:

- **Attend the entire course with a patient**
- Bring a laptop computer
- Perform a supervised fitting
- Pass an exam

Socket Requirements:**Transhumeral**

The patient should have a well-fitting, well-suspended test socket. If using suction, the electrodes should be formed into the test socket. A well fitting test socket should not gap at the proximal lateral trimline, provide rotational stability, and maintain good contact along the lateral shaft of the humerus, with no pressure on the distal humerus. Suspension is also your responsibility to provide and bring with you. Recommendation for a Transhumeral casting technique is available upon request.

Shoulder Disarticulation or Higher level

- The patient should have a well-fitting, well-suspended test socket
- Shoulder joint needs to be securely attached
- The humeral section will be attached to the elbow through a heat formable alignment tool provided with the elbow.

Fees and Accommodations

- Course tuition: \$200 per practitioner
- Practitioners and patients are responsible for their own travel arrangements. For courses held at an Otto Bock Education Center, Otto Bock will cover hotel guest room charges. Otto Bock will cover two nights for this course. You are responsible for any additional nights and all incidental charges. We will provide you with information on hotel accommodations after receiving your registration form.

At the training course, the Dynamic Arm will be fitted, aligned and adjusted to your patient. By the end of the course, your patient should be ready to return home, and you will be able to finish the prosthesis. Or, if you prefer, you may choose to use the fabrication services offered by our Technical Center.

If you are interested in purchasing this innovative product and have a prospective patient in mind, please fill out and fax back the attached registration and component selection forms. The forms must be received 3 weeks prior to the course date.

We look forward to receiving your registration forms and seeing you at a DynamicArm training course in the near future.



QUALITY FOR LIFE

2010 Otto Bock Dynamic Arm Qualification Course Registration 15 CEU's Awarded

Location: _____ Date: _____

Duration: 2 days, 8:00 am – 5:00 pm both days

Requirements:

- Practitioner must be certified and/or licensed in order to attend the Dynamic Arm course
Myobock Certification prerequisite within 3 years.
Purchase of a Dynamic Arm.
Class size limited to 6 Practitioners/3 Patients (2:1 ratio).
This registration form MUST BE received at least 3 weeks prior to course date.

Prosthetist name and title (as you have it appear on certificate): _____

Patient name: _____

Facility name: _____

Address: _____

City and State and Zip: _____

Phone number: _____ Fax number: _____

Email Address: _____

Customer Account Number: _____ Purchase Order Number: _____

If an additional practitioner plans to attend the course, please provide the following information:

Practitioner Name & Title: _____

I give Otto Bock permission to email or fax information to me at the address/number listed above:

Signature: _____

Form containing two columns of text: 'I understand that a \$200 tuition fee...' and 'Please indicate if you or your patient have any food preferences:'. Includes checkboxes for 'Vegetarian' and 'Other:'. Also includes questions about handicap accessible rooms and wheelchair accessible transportation.

Please fax your completed registration form and patient information form to Julie Sohn at 763-519-6152 no later than 3 weeks prior to the course date.

(The following component selection form must accompany this registration form.)



Otto Bock Dynamic Arm Component Selection Form

Facility name: _____ Prosthetist name: _____

Patient name: _____ Male _____ Female _____

Amputation Level: _____ Right _____ Left _____

Component Selection

The components selected will be delivered to the course unless otherwise specified.

Dynamic Arm

- 12K100=50 Color #4
- 12K100=50 Color # 11 or Color #15
(special order may be required)
- 12K100=45 Color #4 (Size 7 ¼ hand)
- 12K100=45 Color # 11 or Color #15
(special order may be required)

SensorHand Speed

- 8E38=8 QD
- Hand Size 7 ¼ 7 ¾ 8 ¼

MyoHand VariPlus Speed

- 8E38=9 QD
- Hand Size 7 ¼ 7 ¾ 8 ¼

Greifer DMC VariPlus

- 8E33=9 QD

Cosmetic Glove

Color # _____
Quantity _____

Wrist Unit

- 10S1=45 or 50 Lamination ring is included with the DA package
- 10S17 Electric Wrist Rotator
OR
- 10S4 Coupling piece
- 9E169 Coaxial plug

Input Devices

- Electrodes 13E200=60 (Std. Mount)
_____ Quantity
- Electrodes 13E202=60 (Suction Mount)
_____ Quantity
- 9x50 linear transducer (harness version)
- 9x52 linear transducer (socket version)
- 9X51 Step Transducer (harness version)
- 9X53 Step Transducer (socket version)
- 13E129=G600 Electrode cable
_____ Quantity
- 9X18 Cable pull switch
- 9X14 Harness pull switch
- 9X25 Rocker switch
- 9X37 Pressure switch
- 13E99=1200 Electrode cable

Bluetooth Adapter (required)

- BionicLink PC 60X5